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Biochemical sensing exploiting plasmonic sensors based on gold nanogratings and polymer optical fibers

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In this work, we present a novel biochemical sensing approach based on a plasmonic sensor chip, combined with a specific receptor, excited and interrogated via a custom 3D-printed holder through a transmission-based experimental setup, exploiting polymer optical fibers. The setup is designed to measure a disposable plasmonic chip based on a gold nanograting fabricated on a polymethylmethacrylate substrate. The examined sensor configurations here presented are simulated, realized, and experimentally tested. More specifically, first, a numerical analysis is carried out by changing several sensor parameters, then an experimental optical characterization of different sensor configurations is reported. Finally, to test the biosensing capabilities of the proposed method, as a proof of concept, we deposit on the best sensor configuration a biomimetic receptor specific for bovine serum albumin detection. The experimental results demonstrate that the proposed sensor shows an ultra-low limit of detection, equal to about 37 pmol/L. © 2021 Chinese Laser Press

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1. INTRODUCTION

The development of innovative sensors benefiting from phenomena such as surface plasmon resonance (SPR) and localized SPR (LSPR) has been continuously spreading in the scientific community in the last decades [1–7]. Plasmons are coherent oscillations of free electrons propagating at the interface between a dielectric medium and a thin metal film (nano-film); in particular, SPR is generated from continuous metallic nanofilms, while LSPR can be excited, for instance, on metallic nanoparticles or nanostructures so inducing a strong localized enhancement of the electromagnetic field. Both plasmonic techniques have largely demonstrated their appropriateness for a wide range of application fields, such as biochemical species detection, where high sensitivity and real-time, label-free detection are strictly required [8–18].

Recently, biosensors based on plasmonic platforms have been realized in several types of optical fibers (silica, plastic, or specialty) [19–21]. These kinds of sensors may reduce the dimensions and price of the entire sensor system. Generally, optical fiber sensors are defined as intrinsic or extrinsic, according to the interaction of the fiber with the analyzed medium (intrinsic) or its use as a mere waveguide allowing the launch of light to the sensing region and its collection (extrinsic) [22]. Recent developments in nanostructure manufacturing technologies [23,24], such as electron-beam and ion-beam lithography, paved the way to novel sensing approaches and applications [25–29]. Moreover, optical biosensors based on plasmonic nanostructures have prompted extensive attention and have been largely investigated in the last years [30–33]. The performances of these kinds of sensors are strongly dependent on the size, shape, and periodicity of metallic nanostructures [3]. In particular, with a special focus on nanograting structures, both theoretical and experimental analysis can be found in literature [34–39].

In general, to test these sensing platforms, two kinds of experimental configurations can be deployed, one reflection based and the other one transmission based. The choice is typically dependent on experimental evaluations such as substrate transparency and instrument setup. For instance, Gao *et al.* [40] recently presented a plasmonic platform based on twodimensional gold nanohole arrays fabricated by a nanoimprint lithography method. In this case, they implemented a laboratory-built reflection-based system to tune the performances and to test their sensor. Although these kinds of setups are usually quite simple and cost effective, the main issue is related to the "dropping" approaches used to allow interaction between the sensor's surface and the liquid sample containing the analyte of interest [40-43].

On the contrary, Chamanzar *et al.* [44] developed a hybrid plasmonic–photonic LSPR sensor, based on a silicon nitride ridge waveguide integrated with gold nanorods on top. To test their sensors, they used a transmission-based experimental setup coupled with a microfluidic system. The latter is widely used in these kinds of setups [44–47], making it possible to overcome the aforementioned problem even if the downside is represented by a more complex experimental measurement system.

In this work, we have designed, developed, and tested plasmonic sensor configurations based on gold nanogratings (GNGs), fabricated by electron-beam lithography (EBL) on the surface of a polymethylmethacrylate (PMMA) substrate and monitored by a custom setup, realized with polymer optical fibers (POFs) and a 3D-printed holder. In other words, a novel transmission extrinsic optical fiber sensor is presented. This sensing approach could be used in those biochemical applications where a small size area to functionalize is required, together with higher sensitivity.

The structure parameters of the proposed plasmonic sensor chip have been here optimized by performing numerical simulations to achieve the best configuration in terms of sensor performances. Subsequently, several plasmonic sensor chips have been fabricated and experimentally tested. More specifically, the realized sensor configurations have been optically characterized by different water–glycerin mixtures. After these preliminary experimental tests, a biomimetic receptor, a molecularly imprinted polymer (MIP), specific for bovine serum albumin (BSA), was deposited upon the best plasmonic sensor configuration to test its biochemical sensing capabilities. The binding tests were carried out and described. Finally, a comparative analysis with other BSA sensors is reported.

2. NUMERICAL ANALYSIS

The sensing method here presented is based on a plasmonic phenomenon. In general, the dispersion relation that links the surface plasmons (SPs) wavenumber k_{SP} to an incident light angular frequency (ω) is given by the following equation [48]:

$$k_{\rm SP} = \frac{\omega}{c} \sqrt{\frac{\varepsilon_m \varepsilon_d}{\varepsilon_m + \varepsilon_d}},\tag{1}$$

where *c* is the speed of light, ε_m is the metal permittivity, and ε_d is the dielectric permittivity. In a nanograting-based sensor, both SPs and localized SPs (LSPs) can be excited, and their mutual interaction can give rise to hybrid modes [48,49], or, alternatively, in the case of normal incidence, a subwavelength periodic grating can couple the incident light to the SPs, in a way similar to the prism, according to Eq. (2) [50,51]:

$$k_m = k_{\rm SP} + mG, \qquad m = 0, \pm 1, \pm ..., \pm N,$$
 (2)

where k_m is the transverse component of the incident wave vector, and $k_{\rm SP}$ is the SPs wave vector. The integer *m* denotes different diffraction orders of the grating, whereas $G = 2\pi/\Lambda$ is the reciprocal lattice vector of the grating, whose period is equal to Λ .

In the study cases herein reported, the periodicity of the grating is comparable with the operating wavelength, and so hybrid modes can be excited. In particular, when the LSP resonance condition is satisfied as well, the SPs dispersion relation is altered [52]. In general, to describe the excitation of LSPs, ε_d can be replaced by the effective medium permittivity ε_{eff} in Eq. (1). This approach can be used for subwavelength structures, whereas, generally, the LSPs dispersion relation is not given in a closed form [48,49,53].

For this reason, to optimize the optical response of the proposed plasmonic sensor, we have performed numerical simulations by using COMSOL Multiphysics software, which is based on the finite element method (FEM). A schematic cross section of the plasmonic sensor GNG-based structure is described in Fig. 1, where the parameters of interest are reported (W, P, S, T). In this section, several numerical analyses are obtained by changing these parameters separately. In the reported simulations, the best performances have been obtained by the sensor configuration with W = 400 nm, $P = 1 \mu$ m, and T = 40 nm.

For the studied sensors, to establish the best configuration, we have evaluated the bulk sensitivity S_n and the full width at half maximum (FWHM), which can be used to calculate the signal-to-noise ratio (SNR). The sensor parameters are defined as recalled in Eqs. (3) and (4) [54], respectively. In particular, the sensitivity can be calculated as

$$S_n = \frac{\delta \lambda_{\rm res}}{\delta n_{\rm s}},\tag{3}$$

whereas, SNR can be defined as

$$SNR(n) = \left(\frac{\delta\lambda_{res}}{\delta\lambda_{FWHM}}\right)_n,$$
 (4)

where $\delta \lambda_{res}$ is the variation in resonance wavelength, δn_s is the change in refractive index of the bulk solution, and $\delta \lambda_{FWHM}$ is the FWHM variation of the plasmonic curves.

A. Numerical Results Relative to Configurations with Different Periods and Fixed Width

In periodic nanogratings, the performances are strongly dependent on the period P [37] and, by varying this parameter, it is also possible to tune the resonance wavelength value [35,37]. In a first step, by keeping fixed the width W = 400 nm and the gold film thickness T = 40 nm, we have performed numerical simulations changing the period P. In particular, we have set a unique angle of excitation (worst case), equal to 90° with respect to the nanograting. For instance, in Fig. 2 are reported



Fig. 1. Schematic cross section of the studied plasmonic GNG-based sensors.



Fig. 2. Plasmonic spectra obtained with water (n = 1.332) as surrounding medium for three different period *P* values: 500 nm, 1 μ m, and 1.5 μ m.

the plasmonic spectra relative to three different P values (500 nm, 1 μ m, and 1.5 μ m), considering a refractive index (*n*) of the surrounding medium equal to 1.332 (i.e., water). As is clear in Fig. 2, by increasing the period, the resonance wavelength increases (redshift), and the shape of the resonance changes.

In particular, the resonance peak depth and the FWHM of the curves change as a function of the considered parameter. As shown in Fig. 2, when the period P decreases, the FWHM decreases too, while the peak depth increases. These aspects are essentially related to the change in mutual couplings between the nanostripes.

Standing these preliminary observations, we have conducted numerical simulations by changing the refractive index of the external medium (the bulk solution) to find the best configuration. In Fig. 3(a), for three values of the period *P* (500 nm, 1 µm, and 1.5 µm), the absolute value of the variations in resonance wavelength ($|\Delta\lambda|$), calculated with respect to water (n = 1.332), versus the refractive index, along with a linear fitting of the simulated data, is reported; in addition, Fig. 3(b) shows the FWHM ($\lambda_{\rm FWHM}$) versus the refractive index for the same aforementioned configurations. From Eq. (3), the sensitivity can be approximated by the slope of the linear fitting functions reported in Fig. 3(a) [54].

As can be seen in Fig. 3, a decrease in the period P value corresponds to narrower plasmonic curves (FWHM decreases), even if the downside is represented by a worst sensitivity. The configurations with $P = 1 \ \mu m$ and $P = 1.5 \ \mu m$ present a quite similar sensitivity, but the first is preferred because it shows lower FWHM, which means a higher SNR.

B. Numerical Results Relative to Configurations with Different Widths and Fixed Period

We have then conducted a similar analysis at varying nanostripe widths W and keeping fixed a period P equal to 1 µm. Also in this case, the gold thickness (T) is fixed to 40 nm. By considering three different values of W (200 nm, 400 nm, and 600 nm), we observe that the configuration with a width of 400 nm presents the best sensitivity, calculated as the slope of the linear fitting functions presented in Fig. 4(a). On the opposite, the configurations with W = 200 nm and W = 600 nm present better SNRs if compared to the one presenting a width equal to 400 nm.



Fig. 3. Numerical results for three configurations with different *P* values (500 nm, 1 μ m, and 1.5 μ m) at a fixed W = 400 nm and T = 40 nm. (a) Absolute value of the variations in resonance wavelength ($|\Delta\lambda|$) calculated with respect to the water (n = 1.332) versus the refractive index along with the linear fitting of the simulated data. (b) Full width at half maximum (FWHM) versus refractive index.



Fig. 4. Numerical results for three configurations with different W values (W = 200 nm, W = 400 nm, and W = 600 nm) at a fixed $P = 1 \ \mu m$ and T = 40 nm. Absolute value of the variations in resonance wavelength ($|\Delta\lambda|$) calculated with respect to the water (n = 1.332) versus the refractive index along with the linear fitting of the simulated data.

C. Numerical Results Relative to Configurations with Different Widths and Fixed Spacing

Moreover, we have also determined how the widths of the nanostripes influence the optical response when keeping fixed the mutual spacing S. To this aim, we have considered three different configurations, W = 200 nm, W = 400 nm, and W = 600 nm, with a spacing S equal to 600 nm, which means also a variable period P equal to 800 nm, 1 µm, and 1.2 µm,



Fig. 5. Numerical results for three configurations with different W values (W = 200 nm, W = 400 nm, and W = 600 nm) at a fixed S = 600 nm and T = 40 nm. Absolute value of the variations in resonance wavelength ($|\Delta\lambda|$) calculated with respect to the water (n = 1.332) versus the refractive index along with the linear fitting of the simulated data.

respectively. For all the simulated configurations, the gold film thickness (T) is fixed to 40 nm.

Figure 5 clearly shows that, when keeping S fixed, the configuration with W = 600 nm presents the worst sensitivity, whereas the one with W = 400 nm is the best one; reducing the width of the nanostripes down to 200 nm leads to an intermediate result.

D. Numerical Results Relative to the Optimal Configuration with Different Gold Thicknesses

Finally, to demonstrate that in the previous simulations the chosen value of the gold thickness is actually the optimum, we have analyzed the influence of the gold film thickness T. In this simulation, the geometric parameters are fixed to W = 400 nm and $P = 1 \ \mu\text{m}$ (optimized structure). To this aim, we report in Fig. 6 the simulated absolute value variation of resonance wavelength in the refractive index range between 1.332 and 1.363 ($|\Delta\lambda_{1.332-1.363}|$), for several gold thicknesses ranging from 30 to 60 nm. As is clear, the optimum is reached when a 40 nm gold thick layer is considered, because it corresponds to a higher variation in resonance wavelength, i.e., to a higher sensitivity.



Fig. 6. Simulated absolute value of the resonance wavelength variation in the refractive index range between 1.332 and 1.363, for different values of gold thickness (ranging from 30 to 60 nm), deposited on the optimized nanograting structure.

3. SENSOR SYSTEM: PLASMONIC PLATFORMS, SETUP, AND RECEPTOR

A. Plasmonic Platforms

The plasmonic GNG-based sensors fabrication is schematically shown in Fig. 7. The initial sample consists of a 10 mm × 10 mm × 0.5 mm PMMA layer (GoodFellow, Huntingdon, England) on which a 220 nm thick positive PMMA e-beam resist (AR-P 679.04, AllResist GmbH, Strausberg, Germany) layer is spun. The nanograting pattern is exposed by taking advantage of the EBL system (Zeiss Supra v35 – Raith Elphy Quantum) with an acceleration voltage of 20 kV, a 7.5 μ m aperture, and a beam current of 20 pA. After the development process, a 40 nm thick gold film is deposited through a sputtering machine (BalTec SCD 500, Schalksmühle, Germany). We have used this fabrication process for all the analyzed sensor configurations, changing only the exposed pattern.

B. Experimental Setup and Binding Measurements Protocol

The experimental measurements relative to the plasmonic GNG sensor have been carried out by using a simple and low-cost transmission-based setup, schematically shown in Fig. 8(a). We have used as a white light source a halogen lamp that exhibits an emission range from 360 to 1700 nm (HL-2000-LL, manufactured by Ocean Optics, Dunedin, FL, USA). The light source is connected through a POF optical coupler (50:50) to two POF patches (1 mm total diameter, PMMA core of 980 µm), one illuminating the sensor with a nanograting and the other illuminating the reference sensor, i.e., a PMMA chip with the same gold film but without the nanograting. Both PMMA chips are kept steady in a specially designed 3D-printed metallic (AISI 316 steel) holder and contained in a specific tank (see Fig. 8). At the output are present two similar POF patches used to collect the transmitted light and send it into two spectrometers that have a detection range from 350 to 1023 nm (FLAME-S-VIS-NIR-ES, manufactured by Ocean Optics, Dunedin, FL, USA). Figure 8(b) shows a detail of the holder adopted to keep both the PMMA chips (with and without a nanograting) in an orthogonal position with respect to the direction of the input/output POFs.

For all the tested configurations, the experimentally measured plasmonic spectra have been obtained by normalizing the transmitted spectra, acquired through the sensor with a nanograting, with respect to the reference sensor.

We have first tested the sensor configurations to obtain the bulk sensitivity (exploiting the water–glycerin mixture) and, for the best configuration, we have also obtained the performances relative to BSA detection (exploiting a specific MIP for selective recognition), in terms of sensitivity at low concentration, limit of detection (LOD), etc.

With particular regards to the binding tests, we have used a standard measurement protocol that can be summarized as follows: first, the holder tank is filled with the analyte solution and is so kept for 10 min to allow interaction between the analyte and the receptor; subsequently, an intermediate washing step is carried out by using Milli-Q water to remove a non-specific binding upon the plasmonic sensor surface; finally, the spectra



Fig. 7. Outline of the plasmonic sensor fabrication.



Fig. 8. (a) Outline of the specially designed transmission-based experimental setup. (b) Zoom on the specially designed 3D-printed metallic (AISI 316 steel) holder with the PMMA chips and POFs.

are acquired with a blank as bulk solution (buffer solution without analyte).

C. Biomimetic Receptor Film

1. Chemicals

Reagents: N,N'-methylene bisacrylamide (BIS) (CAS 110-26-9), Acrylamide (Aam) (CAS 79-06-1), N-tert-butylacrylamide (TBAm) (CAS 107-58-4), 2-hydroxyethyl methacrylate (HEMA) (CAS 868-77-9), ammonium persulfate (APS) (CAS 7727-54-0), N,N,N',N'-tetramethylethylenediamine (TEMED) (CAS 110-18-9), sodium dodecyl sulfate (SDS) (CAS 151-21-3), and phosphate buffer (PB) solution 1.0 M (1 M = 1 mol/L) were from Sigma-Aldrich (Darmstadt, Germany) and used without any further purification. All other chemicals were of analytical reagent grade. The solvent was Milli-Q water.

The BSA (CAS 9048-46-8) and trypsin (CAS 9002-07-7) were from Sigma-Aldrich (Darmstadt, Germany).

MIPs are synthetic receptors capable of recognizing molecules or classes of molecules for which they have been synthesized [55,56]. The synthesis involves the use of a template molecule and suitable functional monomers able to coordinate the target molecule by establishing interactions of various kinds (van der Waals, ionic, dipole–dipole, etc.) forming a complex.

Subsequently, the system is fixed by cross-linking, forming a polymer. Following the extraction of the template, the interaction sites are freed and are able to reversibly recognize the analyte of interest.

In the specific case, this synthetic receptor is made to grow on the Au surface forming a nanometric film. In particular, a recently developed MIP synthesis strategy for proteins, under non-denaturing conditions, is exploited [57]. The preparation steps are summarized below.

First, the optical transducer has been suitably modified with an allyl thiol to covalently bind the polymeric receptor to the gold layer. In particular, the gold surface of the transducer was modified by immersing it in a allyl thiol solution (in which volume fractions of allyl thiol, ethanol, and water are 10%, 80%, and 10%, respectively) for 12 h. Subsequently, the platform was washed with Milli-Q water (flushing 3 mL five times). Through this process, a self-assembled monolayer with a terminal allyl group is formed.

Afterwards, the monomer mixture was prepared: Aam, TBAm, and HEMA were added at 1:0.5:0.6 molar ratio, in 15 mM PB pH 7.4. The final concentration of N,N'-methylene BIS in the monomeric mix was 0.19 M. The pre-polymeric mixture was dispersed by sonication (sonic bath model VWR USC200T) for 10 min and bubbled with N_2 for 30 min at room temperature. The template (BSA protein) was added to the pre-polymeric mixture to the final concentration of 1 µM. Then APS (0.08% weight-to-volume ratio) and TEMED (0.06% weight-to-volume ratio) were added. About 2 µL of the pre-polymeric mixture was dropped over the sensing region and polymerized for 15 min at room temperature, after which the reticulation process was stopped by washing the sensor surface with Milli-Q water. Finally, the template was removed by incubating trypsin 4.2×10^{-8} M for 2 h at room temperature on the sensor surface and then by washing with an SDS 5% (weight-to-volume ratio) solution.

4. RESULTS AND DISCUSSION

A. Optical Characterization of the Proposed Plasmonic GNG-Based Sensor

In this section, the best sensor configuration, obtained by numerical results, is realized (as explained in Section 3.A) and experimentally tested. Figure 9 shows a scanning electron microscope (SEM) image of the fabricated nanograting. In particular, the pattern covers an area of 1 mm² at the center of the PMMA chip; each stripe presents a width of about 400 nm and a total height of about 260 nm, and is spaced from the following of about 600 nm, which means a nanograting period of about 1 μ m.

In a preliminary step, the proposed and developed plasmonic sensor has been optically tested, with the experimental setup reported in Fig. 8, to obtain the bulk sensitivity. The response of the plasmonic sensor, not derivatized with the

Fig. 9. SEM image of the fabricated gold nanograting.

receptor, has been examined by registering the spectra in air and in different water–glycerin solutions (at different refractive indices). In particular, to carry out experimental measurements, the holder tank has been filled with about 1 mL of different water–glycerin mixtures whose refractive indices (n) range from 1.332 to 1.353. These values have been previously determined by an Abbe refractometer (Model RMI, Exacta + Optech GmbH, Munich, Germany).

In Fig. 10(a) are reported the experimentally measured spectra normalized as described in Section 3.B. The resonance wavelength value in the spectrum changes when the refractive index of the solution changes. In particular, when the refractive index increases, the resonance wavelength decreases (blueshift)



Fig. 10. (a) Plasmonic spectra obtained at different refractive indices. (b) Absolute value of the resonance wavelength shift ($|\Delta\lambda|$) with respect to water (n = 1.332) and linear fitting of the experimental values with error bars.

as well as for some LSPR sensors [58,59]. Moreover, a resonance phenomenon is present also when the air (n = 1) is considered as the surrounding medium, i.e., when the holder tank is not filled with any liquid solution.

To evaluate the performances of the proposed sensor, we have estimated the bulk sensitivity by considering a first-order analysis, similar to the numerical analysis. In fact, by using Eq. (3), this parameter can be approximated by the slope of the linear fitting function presented in Fig. 10(b). In particular, in the refractive index range between 1.332 and 1.353, a bulk sensitivity equal to 547 nm/RIU has been obtained.

Table 1 reports a comparative analysis of bulk sensitivity for several plasmonic sensors presented in literature.

B. Experimental Confirmation: Characterization of Non-Optimum Sensor Configurations

By taking advantage of the same technology process described in Section 3.A, we have realized and tested some GNG-based configurations that resulted as non-optimized, according to the numerical analysis carried out in Section 2, to experimentally confirm simulations results.

First, to determine the role of the grating in the plasmonic phenomenon, we have considered two non-periodic configurations, i.e., a "non-periodic configuration 1," where the stripe width is variable, whereas the mutual spacing between the stripes is kept fixed to 600 nm as in the optimized case, and a "non-periodic configuration 2," where the stripe width is equal to 400 nm (as in the optimized case), but the mutual spacing is variable.

The SEM images together with the normalized plasmonic spectra relative to non-periodic configuration 1 and non-periodic configuration 2 are reported in Fig. 11 and Fig. 12, respectively. As is clearly shown in Figs. 11(b) and 12(b), a resonance phenomenon is present in both cases although the periodicity condition of the grating is not satisfied anymore. These results reflect the fact that hybrid modes are excited in this kind of structure, as supposed in Section 2.

Furthermore, we have also realized and tested two periodic configurations, i.e., a "periodic configuration 1," where the grating has a period equal to 1 μ m (like the optimized structure) and a stripe width equal to 600 nm (wider than the optimized configuration), and a "periodic configuration 2," where the grating presents a stripe width equal to about 400 nm (like the optimized structure) and a period equal to about 1.6 μ m, larger

Table 1. Bulk Sensitivity of Several Plasmonic Sensors

Plasmonic Sensor Technology	Bulk Sensitivity [nm/RIU]	Reference
Gold nanocone arrays on glass substrate	417	D. Kawasaki <i>et al.</i> [41]
Gold nanohole arrays	481	H. Im <i>et al.</i> [45]
Periodic gold nanorings on quartz substrate	544	S. Wang <i>et al.</i> [60]
Nanocavities array on glass substrate	360	Cattoni <i>et al.</i> [61]
Gold nanograting on PMMA slab waveguide	547	This work



Fig. 11. (a) SEM image and (b) normalized plasmonic spectra at varying external refractive index relative to non-periodic configuration 1.

than the optimized configuration. Figures 13 and 14 report the SEM images and plasmonic spectra relative to periodic configuration 1 and periodic configuration 2, respectively.

As is clear, a blueshift of the resonance wavelength at the increasing external refractive index is observed in all the considered cases, except in the periodic configuration 2. In fact, the latter still presents a slight resonance phenomenon when air is considered as the surrounding medium while, on the contrary, at higher refractive index values (aqueous medium), standing the weak mutual coupling between the nanostripes caused by the very large period, the resonance condition is not satisfied anymore, as clearly shown in Fig. 14(b).

Figure 15 reports the absolute value of the variation in resonance wavelength ($|\Delta\lambda|$) along with the linear fitting of the experimental data for the tested nanograting configurations (optimized and non-optimized), in the refractive index range from 1.332 to 1.353.

As shown in Fig. 15, the introduction of non-periodic or non-optimized structures from the geometrical (i.e., width and spacing) point of view, has led to a considerable drop in the sensitivity calculated for each configuration, as the slopes of the linear fitting functions reported in Fig. 15. On the contrary, the bright side of the non-optimum configurations is mainly linked to a clear improvement in the SNR, in terms of FWHM. This duality between sensitivity and SNR was already highlighted by the simulation results in Section 2.





Fig. 12. (a) SEM image and (b) normalized plasmonic spectra at varying external refractive index relative to non-periodic configuration 2.

C. Binding Test: BSA Detection

The biochemical sensing capabilities of the optimized and developed plasmonic sensor (described in Section 4.A) have been tested by depositing a specific receptor (MIP) for the BSA protein. In particular, the functionalized surface coincides with the one where the nanograting is present [see Fig. 16(a)]. Figure 16(b) shows the normalized plasmonic spectra relative to the GNG-based sensor with the receptor layer, at different BSA protein concentrations ranging from 0.1 to 1000 nM. As is clear, a blueshift of the resonance wavelength (λ) is observed when the analyte concentration increases (the refractive index of the receptor layer increases when the binding occurs).

Figure 17 shows the absolute value of the resonance wavelength shift with respect to the blank (solution without the analyte), along with the Langmuir fitting of the experimental data and the error bars, in semi-log scale.

For each sample, the experimental measurements were repeated three times, and the maximum error (equal to 0.2 nm) was considered as the error bar. This dose-response curve was fitted by the following Langmuir equation:

$$|\Delta\lambda| = |\lambda_c - \lambda_0| = |\Delta\lambda_{\max}| \cdot \left(\frac{c}{K+c}\right),$$
(5)

where *c* is the analyte concentration, λ_c is the resonance wavelength at the concentration *c*, λ_0 is the resonance wavelength value at zero concentration (blank), and $\Delta\lambda_{max}$ is the maximum

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Fig. 13. (a) SEM image and (b) normalized plasmonic spectra at varying of the external refractive index relative to periodic configuration 1.

value of $\Delta \lambda$ (calculated by the saturation value minus the blank value).

The parameters relative to the Langmuir fitting are listed in Table 2. These values have been obtained by OriginPro software (Origin Lab. Corp., Northampton, MA, USA). As shown in Eq. (5), at low analyte concentration (*c*), i.e., much lower than *K*, the equation is linear, with sensitivity (slope) $|\Delta\lambda_{\text{max}}|/K$, defined as the "sensitivity at low concentration." The LOD has been calculated by the ratio of two times the standard deviation of the blank (standard deviation of λ_0 equal to 0.02 nm) and the sensitivity at low concentration ($|\Delta\lambda_{\text{max}}|/K$ equal to 1.09 nm/nM), and it has resulted equal to about 37 pM.

D. Discussion

1. Comparative Analysis with Other BSA Sensors

To better understand how in the proposed structure the plasmonic phenomenon has been enhanced with respect to other configurations, we have first compared the GNG-MIP-based sensor with another BSA sensor based on an SPR D-shaped POF platform functionalized with the same MIP receptor layer [57].

We have evaluated and compared the LOD for both configurations (SPR-POF-MIP and GNG-MIP based). The SPR-POF-MIP platform shows an LOD equal to about 0.37 μ M [57], whereas the value obtained in the case of the





Fig. 14. (a) SEM image and (b) normalized plasmonic spectra at varying external refractive index relative to periodic configuration 2.

GNG-MIP-based configuration is about four orders of magnitude lower (37 pM).

With regard to the range of BSA detection, it is possible to observe that the SPR-POF sensor is capable of detecting a BSA protein concentration ranging from 0.37 μ M (LOD) to about 6.5 μ M (value of saturation); on the contrary, the nanograting-based sensor has shown a range of BSA detection between 37 pM (LOD) and 100 nM (value of saturation). So, depending on the particular requirements, both configurations can be used: if a very low sensitivity is strictly required, the plasmonic GNG-MIP-based configuration is preferred because of a very



Fig. 15. Absolute value of the variation in resonance wavelength $(|\Delta \lambda|)$ calculated with respect to water (n = 1.332) for the optimized and non-optimized configurations.



Fig. 16. (a) Outline of the functionalized surface and (b) plasmonic spectra obtained at different BSA protein concentrations. Inset: zoom-in of the resonance region.

low LOD; on the contrary, the SPR-POF configuration is preferable when higher concentrations have to be analyzed.

Finally, to compare the proposed sensor with other BSA sensors, based on different platforms or receptors, Table 3 summarizes the main biosensing parameters relative to several sensors presented in the literature. In particular, the developed GNG-based sensor approach presents, as a main advantage, label-free detection and lower LOD if compared to the



Fig. 17. Absolute value of resonance wavelength variation $(|\Delta\lambda|)$, with respect to the blank, versus the concentration of BSA protein, with the Langmuir fitting of the experimental values and error bars, in semi-log scale.

Table 2. Parameters of the Langmuir Fitting (GNG-MIP-Based Platform)

$\Delta \lambda_{\max}$ [nm] K [nM]		Statistics	
	<i>K</i> [nM]	Red. Chi-Sqr	Adj R-Square
3.31 ± 0.02	3.04 ± 0.67	0.009	0.99

fluorescent-based sensors proposed in Refs. [62,63]. When comparing it with other plasmonic-based techniques [57,64,65] a clear improvement in terms of LOD has been obtained with respect to Refs. [57,64], whereas this value is lower with respect to the one calculated in Ref. [65], where a bioreceptor is used. This kind of receptor, if compared to a synthetic receptor (MIP), presents as a main advantage of very good sensitivity because the binding occurs closest to the metal–dielectric interface, whereas it presents also diverse disadvantages. For instance, MIP receptors are easier and faster to prepare with respect to bioreceptors; moreover, they present also longer durability, better behavior in harsh environmental conditions, and the possibility to use them in industrial manufacturing [55,56].

2. Reproducibility and Reusability of the Proposed Sensor

To check the reproducibility of the proposed sensor, we have performed several tests from both optical and biosensing sides. In particular, we have built and tested the optimized sensor configuration three different times obtaining a maximum variation in resonance wavelength, when water (n = 1.332) is considered as the surrounding medium, equal to 0.2 nm [error bar considered in Fig. 10(b)]. Moreover, we have obtained the same maximum variation (\cong 0.2 nm) when repeating the measurements on the same optical sensor and in the same conditions mentioned before.

We have conducted a similar analysis also when the sensor is derivatized with the synthetic receptor, in particular by filling the holder tank with a blank solution (buffer solution without analyte).

Furthermore, the proposed biosensor can be reutilized since it is possible to regenerate the MIP receptor by using the same extraction procedure described in Section 3.C. This aspect has been experimentally verified, and the obtained results testify to the goodness of the regeneration process.

Table 3.Comparative Analysis among Several SensorConfigurations for Selective BSA Detection

	BSA Detection		
Configuration	LOD	Range	Reference
SPR-POF-MIP	0.37 µM	0.37–6.5 μM	[57]
Fluorescence sensor	10 nM	0.01–2 μM	[62]
Aggregation-induced	0.4 μM	0.4–1.5 μM	[63]
emission biosensor			
coupled with			
graphene-oxide			
SPR-MoS ₂ optical fiber	4.36 nM	4.36–750 nM	[64]
LSPR based on bimetallic nanoparticles	0.15 pM	150–15,000 pM	[65]
GNG-MIP-based	37 pM	0.037–100 nM	This work

5. CONCLUSION

A novel sensing approach, based on GNGs on PMMA chips monitored through a custom 3D-printed holder combined with POFs, has been exploited. In particular, we have conducted theoretical and experimental studies to establish the best plasmonic sensor configuration, obtaining a bulk sensitivity of about 547 nm/RIU.

As a proof of concept, we have also used it as a biochemical sensor by functionalizing the nanograting surface with a synthetic receptor specific for BSA protein. In such a way, we have obtained an LOD equal to about 37 pM. This value is four orders of magnitude lower than the one obtained with another biochemical sensor based on an SPR-POF probe, functionalized with the same MIP receptor. Moreover, the obtained LOD is lower than the one reported by other BSA sensors.

The proposed sensing approach presents also other advantages in terms of capability of tuning the sensor's performances, by changing the patterns/materials, and of economic aspects, as well. In fact, with regard to the optical transducer, the nanostructures can be realized by exploiting processes typical of microelectronics, so leading to economic advantages of largescale production; on the other hand, the quantity of polymer, which is obviously related to the sensitivity area, affects the total cost of the biochemical sensor. For instance, in the case of the SPR-POF-MIP sensor, the sensitivity area is 10 mm² against an area of 1 mm² for the proposed GNG-MIP sensor. This aspect takes on a noticeable importance when expensive molecules, such as the SARS-CoV-2 spike protein, are used as templates for MIPs [57].

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Data Availability. Data underlying the results presented in this paper are not publicly available at this time but may be obtained from the authors upon reasonable request.

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