Optical trapping and orientation of *Escherichia coli* cells using two tapered fiber probes

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We report on the optical trapping and orientation of *Escherichia coli* (*E. coli*) cells using two tapered fiber probes. With a laser beam at 980 nm wavelength launched into probe I, an *E. coli* chain consisting of three cells was formed at the tip of probe I. After launching a beam at 980 nm into probe II, the *E. coli* at the end of the chain was trapped and oriented via the optical torques yielded by two probes. The orientation of the *E. coli* was controlled by adjusting the laser power of probe II. Experimental results were interpreted by theoretical analysis and numerical simulations. © 2015 Chinese Laser Press

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1. INTRODUCTION

Manipulation of single cells is of great importance in biomedical research, microbiology, cell-cell interaction, and microbiology. Trapping and orientation of individual nonspherical bacteria can promote the study of the interaction between specific regions of biological objects, which provides an efficient method to observe and describe the behavior of single cells and, further, to study the dynamics of bacteria populations [1,2]. Thus, it is of great importance in understanding the mechanisms of cell function [3]. In addition, scanning the angle between the long cell axis and the optical axis of the optical tweezer may allow for reconstruction of the three-dimensional structures using standard computerized tomography methods [4]. Moreover, when the cell was illuminated in different orientations, by studding the scattering light of different orientation, more information on the morphology of the cell can be obtained which can be used to discriminate between different cell types or, more importantly, between different cell states [5]. One of the most widely investigated nonspherical bacteria is Escherichia coli (E. coli) cells due to their critical role in biological engineering and industrial microbiology [6,7]. Some challenges, however, exist in realizing stable trapping and controllable orientation of *E. coli* cells. First, the *E. coli* cells in liquids swim in two patterns, "runs" and "tumbles" [8,9], which are related to the rotation direction of the flagella [10]. Second, the E. coli cells are strongly affected by Brownian motion in liquids due to their nanometer size [11]. To solve these challenges, optical methods based on resonant optical antennas [11] and optical tweezers [4,12] have been proposed to trap and orientate E. coli cells. However, the operations were limited to a fixed substrate or a specific depth of cell solutions, and the bulk structure of the optical system and focusing objective make it difficult to move and focus. Moreover, the difficulty in penetrating thick samples by the focus generated by the objective make

it difficult to apply the system to thick samples. Fortunately, optical fibers provide an alternative approach to manipulate E. coli cells [13–15]. Among them, the fiber probe is a miniaturized and highly flexible tool for particle manipulation because light beams can be simply focused by the tip of the probe without the use of complicated optical components such as high-numerical-aperture objective. However, with only one laser beam applied for the cell manipulation, the orientation will only be determined once the cells are trapped [12,13], and therefore the accessible rotational axes or feasible angles are restrained. In this work, we report on the optical trapping and orientation of E. coli cells using two tapered fiber probes. With the 980 nm laser beams injected into the probes, an E. coli cell chain was formed and trapped at the tip of one probe while the cell at the end of chain can be controllably orientated by adjusting the power injected into the fiber probes.

2. RESULTS

Figure 1 shows the experimental scheme. Two probes with different divergence angles were placed in an E. coli solution [Fig. 1(a)], with an angle of 150° between the probe axes. After launching a laser beam into probe I, an E. coli chain consisting of three cells was formed at the tip of probe I [Fig. 1(b)]. Another beam was then injected into probe II. Due to the superposition of the two beams, the energy density at the intersection point of two probes, i.e., point O in Fig. 1(a), was higher than those around it, resulting in a much stronger gradient force than the scattering force. Therefore, an E. coli cell can be trapped by the gradient force at point O and the orientation of the cell can be realized by adjusting the powers in the two probes. At $P_2 > P_1$, the *E. coli* at point *O* will be orientated with its axis along probe II due to the restoring torque [Fig. 1(c)], while at $P_1 > P_2$, the cell will be orientated along probe I [Fig. 1(d)]. The experimental setup is schematically



Fig. 1. Schemes for the experimental model and setup. (a) Experimental model. The point O is the intersection point of two fiber probes at which the *E. coli* cell will be trapped. (b) An *E. coli* cell chain was formed with a laser beam launched into probe I. (c) The *E. coli* cell is orientated along the axial of probe II when $P_2 > P_1$. (d) The cell is orientated along probe I when $P_1 > P_2$. (e) Experimental setup. Insets I and III indicate the optical microsscope images of probe II and probe I, respectively. Inset II shows the scanning electron micrograph of the *E. coli* cells.

shown in Fig. 1(e). Two laser beams at 980 nm wavelength (with a very weak absorption by E. coli cells) were launched into the two probes. The probes were fabricated by drawing single-mode fibers (connector type, FC/PC; core diameter, 9 µm; cladding diameter, 125 µm) through a flame-heating technique. Fibers I and II were fixed by two tunable microstages I and II, respectively. The lengths of the tapered part and the fiber stick out of the holding stage were about 75 µm and 9 cm, respectively. To decrease the oscillations in our experiment due to the environmental fluctuations, each fiber probe was sheathed by a glass capillary (inner diameter, 0.9 mm; wall thickness, 0.1 mm; length, 12 cm). One side of the glass capillary was fixed on the stage while the other side was stuck out. The length of the probe outside the capillary was about 2 mm. The probes were immersed in the E. coli solution. An optical microscope with a CCD camera was used for real-time monitoring and image capturing.

At the beginning of the experiment (t = 0), laser I was turned on to launch a beam of 25 mW into probe I while no laser was launched into probe II, i.e., $P_1 = 25$ mW and $P_2 = 0$ [Fig. 2(a)]. *E. coli* cells were trapped one after another by the optical forces generated by probe I and gradually formed into a cell chain. At t = 2 s, a chain consisting of three *E. coli* cells was formed [Fig. 2(b)]. At t = 3 s, laser II was also turned on to launch a beam of 20 mW into probe II,



Fig. 2. Optical microscope images for trapping and orientation of the *E. coli*. (a) At t = 0 s, turning on the 980 nm laser of 25 mW into probe I, the cells began to be trapped one after another. (b) At t = 2 s, a cell chain consisting of three *E. coli* cells was connected to the tip of probe I. (c) At t = 3 s, after a laser beam of 20 mW was injected into probe II, the last *E. coli* of the chain was pulled away from the chain. (d) At t = 3.3 s, the angle between the axis of the *E. coli* and probe II (d) was -19° . (e) At t = 4.2 s, the input power of probe II was increased from 20 to 35 mW and the cell was orientated along probe II with θ of 0. (f) At t = 6 s, the input power of probe II was decreased from 35 to 15 mW and the cell was not extended along probe I with θ of -30° .

i.e., $P_1 = 25$ mW and $P_2 = 20$ mW. The *E. coli* at the end of the chain was pulled away from the chain by the optical force from probe II [Fig. 2(c)], and began to be rotated anticlockwise. At t = 3.3 s, the azimuthal angle of the *E. coli* θ , which is defined as the angle between the axes of the *E. coli* and probe II, was -19° [Fig. 2(d)] and the orientation became stable. At t = 4.2 s, with P_2 increased from 20 to 35 mW, the cell was finally oriented along the axis of probe II, i.e., $\theta = 0$ [Fig. 2(e)].

At t = 6 s, with the power of probe II decreased from $P_2 = 35$ to 15 mW, the *E. coli* was rotated clockwise [Fig. 2(f)] and kept orientated along the axis of probe I [Fig. 2(g)], i.e., $\theta = -30^{\circ}$ again.

3. ANALYSIS AND DISCUSSION

To interpret the phenomena just described, simulations were performed based on a finite element method (COMSOL Multiphysics 4.3b). In the simulations, the diameter of probe I was set as 4 μ m at the input port and then linearly decreased to 2 μ m within a length of 15.7 μ m, with a parabolic extremity. The diameter of probe II was set as 8 μ m at the input port and then linearly decreased to 4 μ m within 10.3 μ m. The axis of probe II was along the X direction and the angle between the axes of the two probes was 150°. The *E. coli* cell was treated as a rod (diameter, 500 nm; length, 2 μ m) with two hemispherical caps. The refractive indices are 1.33, 1.39,



Fig. 3. Simulated distributions of energy density for the two probes. (a) Energy density distribution of probe I. (b) Energy density along the axis of probe I. (c) Energy density distribution of probe II. (d) Energy density along the axis of probe I.

and 1.44 for the water, E. coli, and probes at the laser wavelength of 980 nm. Distributions of energy density for the two probes were obtained by the simulations (Fig. 3). When only laser I was launched into probe I, the energy was concentrated near the tip of probe I [Fig. 3(a)] with a focal plane at X =5.5 μ m [Fig. 3(b)], which results in a strong gradient force exerted on the E. coli. When only laser II was launched into probe II, the energy was concentrated at a position further away from the tip of probe II [Fig. 3(c)], with a focal plane at $X = 0.1 \,\mu\text{m}$ [Fig. 3(d)]. The light output from probe I was focused nearly at the tip while the light from probe II was focused 3.6 µm away from the tip, which is attributed to the different profiles and sizes of the two probes. As a result, probe I was used to form and trap a cell chain of E. coli cells while probe II was used to manipulate the single cell at the end of the chain.

The optical force (\mathbf{F}_O) exerted on the *E. coli* can be calculated by integrating the time-dependent Maxwell stress tensor \mathbf{T}_O around the *E. coli* with a closed surface *S* [16,17]:

$$\mathbf{F}_{O} = \oint_{S} (\langle \mathbf{T}_{O} \rangle \bullet \mathbf{n}) \mathrm{d}S, \qquad (1)$$

where **n** is the surface normal vector. The optical torque **T**, which determines the orientation of the *E*. *coli* cell, can be calculated by [18]

$$\mathbf{T} = \int \mathbf{r}_i \times \mathrm{d}\mathbf{F}_{Oi},\tag{2}$$

where $d\mathbf{F}_{Oi}$ is the optical force element at an arbitrary point *i* within the *E. coli* cell that interacts with light, and \mathbf{r}_i is the position vector point from the center point of the *E. coli* cell where $d\mathbf{F}_{Oi}$ is generated. Figure 4(a) shows the calculated optical torque on the *E. coli* cell as a function of the azimuthal angle θ with respect to the +*X* direction. The inset of Fig. 4(a) describes the calculation model. For probe I, **T** is 0 when $\theta = -120^\circ$, -30° , and 60° . In the regions of $-120^\circ < \theta < -30^\circ$ and $60^\circ > \theta > -30^\circ$, the values of **T** are positive and negative so that the *E. coli* is rotated anticlockwise and clockwise, respectively. For probe II, **T** is 0 when $\theta = 0$, -90° , and 90° . In the regions of $-90^\circ < \theta < 0$ and $90^\circ > \theta > 0$, the values of **T** are positive and negative so that the *E. coli* is rotated anticlockwise and clockwise, negative and negative so that the *E. coli* so that the *E. coli* so that the *E. coli* here is no solved anticlockwise and clockwise, respectively. For probe II, **T** is 0 when $\theta = 0$, -90° , and 90° . In the regions of $-90^\circ < \theta < 0$ and $90^\circ > \theta > 0$, the values of **T** are positive and negative so that the *E. coli* is rotated anticlockwise and clockwise, respectively. Therefore, the *E. coli* trapped by probes I and II tends to be rotated



Fig. 4. Optical forces and torques. (a) Optical torques and rotational potential energy as a function of azimuthal angle θ . The inset shows the calculation model. The *E. coli* is orientated with an angle θ to the axis of probe II. Point *i* indicates the arbitrary interaction point with a position vector \mathbf{r}_i from the central point of the *E. coli*. (b) Simulated energy density distributions for *E. coli* chains consisting of 1–4 cells. (c) Energy density distribution along the axis of probe II with cell numbers of 0, 1, 2, and 3. The points A, B, and C were the positions of the cell chain extremities. X = 1.1 was the *X* coordinate of the point *O*. (d) Calculated resultant force (F) exerted on the last *E. coli* chain as a function of the *E. coli* number (*N*). The inset shows the calculation model.

toward $\theta = -30^{\circ}$ and $\theta = 0$, respectively. The rotational potential energy U of the two probes were evaluated by integrating **T** with respect to θ . For stable trapping, U must overcome the thermal energy $k_b T$ [19], i.e., $|U| \gg k_b T$, where k_b was the Boltzmann constant and T was the absolute temperature of the solution. In this work, U has to satisfy that $|U| \ge 100k_bT = 4.14 \times 10^{-19}$ J. For probes I and II, U reaches minimum at $\theta = -30^{\circ}$ and $\theta = 0$, respectively, confirming that $\theta = -30^{\circ}$ and $\theta = 0$ are the most stable orientations for the *E*. coli trapped by probes I and II, respectively. E. coli cells will be trapped at the axis of either probe by the optical force and rotated by the optical torque until the axis of the E. coli coincides with the probe axis. With an input power of 25 mW, four *E. coli* cells can be trapped by the probe [13]. Figure 4(b) shows the simulated energy density distributions of E. coli cell chains consisting of 1–4 cells at an input power at 25 mw. Light was confined in the E. coli cells and propagated along the chain, indicating that the E. coli cells trapped by probe I can be seen as the extension of the fiber tip, resulting in more E. coli cells being trapped. Figure 4(c) shows the energy density distribution along the axis of probe I with cell numbers of N = 0, 1, 2, and 3. When the number of the *E. coli* chain is increased from 0 to 3, more energy will be concentrated along



Fig. 5. Simulations for the orientation process. (a) Energy density distribution for $P_1 = 25$ mW and $P_2 = 20$ mW at $\theta = 0$. (b) Energy density distribution along the axes of the probes projected onto the X coordinate. (c) Optical torques on the *E. coli* as a function of azimuthal angle θ . (d) Rotational potential energy U as a function of azimuthal θ .

the axis of the probe. As a result, for probe I with a cell chain formed at the tip, the optical intensity at point O is stronger than that without a chain. Figure 4(d) shows the calculated resultant optical force (F) exerted on the last *E. coli* of the chain, consisting of 1–4 cells. The optical forces exerted on the last *E. coli* were directed to the probe, which means that this force was the trapping force.

To analyze the orientation process, simulations were then performed by increasing the input power of probe II to 20 mW while keeping the input power of probe I at 25 mW. In the simulation, two E. coli cells were connected with probe I. Figure 5(a) shows the simulated distributions of energy density emitted from the two probes. The distances between the probe tip and the intersection point of probes ($X = 0.6 \mu m$, Y = 0) were $D_1 = 5.9 \ \mu\text{m}$ and $D_2 = 3.4 \ \mu\text{m}$ for probes I and II, respectively. At the intersection point, energy density was higher than those around it because of the superposition of two laser beams. The E. coli near the intersection point will be trapped by the gradient force. Figure 5(b) shows the energy density distributions along the axes of the probes projected onto the X coordinate. The strongest optical intensity was at $X = 1.1 \,\mu\text{m}$ rather than the focus point of probe II $(X = 0.1 \ \mu m)$, indicating that the trapping area of the *E. coli* can be adjusted by changing the positions of the probes. Figure 5(c) shows the calculated optical torques T as a function of input power. For $P_1 = 25$ mW and $P_2 = 20$ mW, the torque **T** is 0 when $\theta = -16^{\circ}$. The torque **T** becomes positive and negative when $\theta < -16^{\circ}$ and $\theta > -16^{\circ}$, respectively, indicating that the orientation is stable at $\theta = -16^{\circ}$. Similarly, for $P_1 = 25 \text{ mW}$ and $P_2 = 35 \text{ mW}$ and for $P_1 = 25 \text{ mW}$ and $P_2 = 15$ mW, the orientation is stable at $\theta = -1.55^{\circ}$ and $\theta = -25.8^{\circ}$, respectively. The rotational potential energy U of two probes reached the corresponding minimum at $\theta = -16^{\circ}$, -1.55° , and -25.8° [Fig. 5(d)], which also indicates the angles for the stable orientations. Note that the experimental results presented in Figs. 2(d) and 2(g) are a bit different from those obtained by calculations. This is because in our models for calculations, the E. coli was simplified as a rod with two hemispherical caps, while actually the E. coli was



Fig. 6. Optical torque **T** and corresponding rotational potential energy U for E. coli as a function of the azimuthal angle θ with different D_2 and input power. (a) Optical torque **T** with $P_1 = 25$ mW and $P_2 = 35$ mW. (b) Rotational potential energy U with $P_1 = 25$ mW and $P_2 = 35$ mW. (c) Optical torque **T** with $P_1 = 25$ mW and $P_2 = 15$ mW. (d) Rotational potential energy U with $P_1 = 25$ mW and $P_2 = 15$ mW.

not always so symmetrical and straight, as shown by the scanning electron micrograph image in the inset II of Fig. 1(e). The slight difference in shape and size also exists in the fiber probe models and the fabricated ones.

To further analyze the optical torques on the *E. coli* with different distance between the probe and E. coli, a series of simulations were performed by changing the position of probe II while fixing probe I at $D_1 = 5.9 \,\mu\text{m}$. Figure 6, as an example, shows calculated optical torque T and corresponding rotational potential U as a function of the azimuthal angle θ . At input power $P_1 = 25 \text{ mW}$, $P_2 = 35 \text{ mW}$, the variation of the values of T for $D_2 = 2.4$, 2.9, and 3.9 μ m is very small compared with those for $D_2 = 3.4 \ \mu m$ [Fig. 6(a)], which indicates that the cell can be rotated toward $\theta = 0$. The corresponding rotational potential U reaches a minimum of less than -1.1×10^{-18} J around $\theta = 0$ [Fig. 6(b)]. The *E. coli* will be orientated along the axis of probe II so that the orientation of the cell can be controlled, with D_2 ranging from 2.4 to 3.9 μ m. Similarly, at input power $P_1 = 25 \text{ mW}, P_2 = 15 \text{ mW}$, the variation of values of T for $D_2 = 2.9$ and $3.9 \ \mu m$ is also very small compared with those for $D_2 = 3.4 \ \mu m$ [Fig. 6(c)]. The corresponding minima of U were -5.22×10^{-19} and -6.1×10^{-19} J [Fig. 6(d)], which indicates that the *E*. *coli* can also be orientated by probe I. For $D_2 = 2.4 \,\mu\text{m}$, the minimum of U was -1.7×10^{-19} J, which was more than -4.14×10^{-19} J. Thus, in this situation, the cell orientation cannot be realized by probe I. This is because the focus of probe II was 1.2 µm away from the intersection point of the axes of the probes in this case. The input power of probe I was decreased and thereby the energy density at the point where the E. coli was trapped was not strong enough to control the orientation of the E. coli.

4. CONCLUSIONS

An optical method for trapping and orientation of *E. coli* cells has been experimentally demonstrated using two probes. By launching a laser beam at 980 nm into probe I, an *E. coli* chain was formed at the probe tip, followed by a trapping and orientation of the *E. coli* at the end of the chain by launching another beam into probe II. The orientation of the $E. \, coli$ was then controlled by adjusting the laser power of probe II. The performance of the method in terms of resultant optical torque and the corresponding rotational potential energy has been numerically analyzed with simulations and calculations. These results are expected to find application in singlecell studies in which optical manipulation of nonspherical bacteria is desired.

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